# Distributed storage systems from combinatorial designs 

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Data in all shapes and sizes!

## NETFLIX

## facebook.

Dropbox

## Microsoft Azure hulu <br> YouTThbe

## Sample statistics from Youtube

## YouTube

$\square$
About Press Copyright Safety Creators Advertise Developers Help

## PRESS

Press room
Campaigns
YouTube for media

## Statistics

B-roll
YouTube blog
YouTube Trends
Developer blog
CitizenTube
Visit us on Google+

## Statistics

## Viewership

- More than 1 billion unique users visit YouTube each month
- Over 6 billion hours of video are watched each month on YouTube-that's alr
- 100 hours of video are uploaded to YouTube every minute
- $80 \%$ of YouTube traffic comes from outside the US
- YouTube is localized in 61 countries and across 61 languages
- According to Nielsen, YouTube reaches more US adults ages 18-34 than any
- Millions of subscriptions happen each day. The number of people subscribing daily subscriptions is up more than $4 x$ since last year


## Several challenges...

- Access needs to be reliable.
- Indeed, server failure is the norm rather than the exception. (Source: hadoop.apache.org)
- System needs to be efficient.
- Failure recovery must be seamless and be inexpensive (bandwidth, time, energy etc.).


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- System needs to be efficient.
- Failure recovery must be seamless and be inexpensive (bandwidth, time, energy etc.).
- Host of other issues such as security, privacy etc.
- Not discussed in this talk...


## Replication vs. coding



Observation
Both systems have same redundancy, but coded solution can recover from any three node failure event.

## Dealing with failure in replication based systems



## Repair in replication based systems



Observation
Repair simply by downloading from the existing copy!

## Repair in coded systems



## Repair in coded systems



- Packet $A 1$ cannot be recovered unless the file $(A 1, A 2, A 3)$ is recovered.
- This requires connecting to three nodes and downloading one packet from each of them.

Coded System

## Can we do better - EVENODD Example [Blaum et al. '95]



Observation
( $n=4, k=2$ ) code. File consists of four packets (A1, A2, A3, A4). File can be reconstructed from any two nodes. Resilient to two failures.

## Can we do better - EVENODD Example



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## Different notions of repair efficiency

- Repair bandwidth: Attempts to minimize the amount of data downloaded for reconstructing the failed node.


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- Repair bandwidth: Attempts to minimize the amount of data downloaded for reconstructing the failed node.
- Local repair: Attempts to minimize the number of nodes contacted for recovering the node.
- There are probably other metrics as well in practice, but these appear to be tractable for code design.


## $(n, k, d)$ - Distributed storage system [Dimakis et al. 10]



- File of size $\mathcal{M}$ packets or symbols stored on $n$ nodes.
- Each node stores $\alpha$ symbols.
- Any user can reconstruct the file by contacting any $k$ nodes. (MDS property)


## $(n, k, d)$ - Distributed storage system [Dimakis et al. 10]



- A failed node can be reconstructed by contacting any $d(d \geq k)$ surviving nodes and downloading $\beta$ packets from each.
- $d$ - repair degree, $\beta$-normalized repair bandwidth.
- Storage capacity vs. repair bandwidth tradeoff was characterized for the case of functional repair.


## ( $n, k, d$ )- Distributed storage system with exact repair

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- Minimum storage regenerating (MSR) point: Store exactly $\mathcal{M} / k$ packets per node, i.e., storage capacity of node is minimum.
- Constructions from [Cadambe et al. 2013 \& others].


## ( $n, k, d$ )- Distributed storage system with exact repair

- Exact copy of the failed node needs to be produced.
- Minimum storage regenerating (MSR) point: Store exactly $\mathcal{M} / k$ packets per node, i.e., storage capacity of node is minimum.
- Constructions from [Cadambe et al. 2013 \& others].
- Minimum bandwidth regenerating (MBR) point: Exactly $\alpha$ packets are downloaded for node regeneration. Equals storage capacity of a node.
- Constructions from [Rashmi et al. 2011 \& others].
- We focus on MBR constructions in this talk.


## Easy repair \& reliable distributed storage systems

- Advantage of replication based systems is easy reconstruction; drawback is storage inefficiency.
- Advantage of coded systems is optimum storage vs. repair bandwidth tradeoff; drawback is complicated reconstruction.


## Easy repair \& reliable distributed storage systems

- Advantage of replication based systems is easy reconstruction; drawback is storage inefficiency.
- Advantage of coded systems is optimum storage vs. repair bandwidth tradeoff; drawback is complicated reconstruction.
- This work - attempt to combine best of both worlds ...


## Systems with exact and uncoded repair [El Rouayheb and

 Ramchandran '10]- Exact repair constructions typically use coding across the source symbols.
- Read-write bandwidth of machines is often a bottleneck in system operation.
- Coding across potentially large $(\approx G B)$ packets can be memory intensive.
- Decoding coded packets can cause an increased repair time [Jiekak et al. '12].


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## Definition (Exact and uncoded repair)

- Exact regeneration by simply downloading symbols from the surviving nodes.
- Operate at the MBR point.
- Table-based repair - new node contacts a specific set of surviving nodes.


## System Architecture



- Outer MDS code.
- Inner fractional repetition (FR) code - specifies placement of symbols on storage nodes.
- File reconstruction if enough symbols are obtained from any $k$ nodes.
- Failure recovery depends on FR code properties.


## System example - complete graph on 5 nodes, $d \geq k$



- File $\left(x_{1}, \ldots, x_{9}\right) \in \mathbb{F}_{q}^{9}, \mathcal{M}=9$. Use $(10,9)$ MDS code to get coded symbols $\left(y_{1}, \ldots, y_{10}\right)$.
- Number of storage nodes $n=5$, number of symbols $\theta=10$.


## System example - complete graph on 5 nodes, $d \geq k$



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- Label edges of the complete graph.


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- Number of storage nodes $n=5$, number of symbols $\theta=10$.
- Label edges of the complete graph.
- Storage nodes store incident symbols.


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 Analyzing file size- $n=5$ nodes, $\theta=10$ symbols.
- Storage nodes are 4 -sized subsets. Using inclusion-exclusion principle

$$
\begin{aligned}
& \begin{aligned}
\left|A_{1} \cup A_{2} \cup A_{3}\right| & =\sum_{i}\left|A_{i}\right|-\sum_{i<j}\left|A_{i} \cap A_{j}\right|+\left|\cap_{i} A_{i}\right| \\
& =3 \times 4-\binom{3}{2}+0=9 .
\end{aligned} \\
& \text { Thus, } k=3 .
\end{aligned}
$$

- Repair degree $d=4$.


## Failure analysis



- Suppose node $V_{1}$ fails.


## Failure analysis



- Suppose node $V_{1}$ fails.
- One symbol from all the other nodes is needed for recovery.
- Need to contact at least $k$ nodes.


## FR codes from combinatorial designs - Fano plane



- File $\left(x_{1}, \ldots, x_{6}\right) \in \mathbb{F}_{q}^{6}, \mathcal{M}=6$. Use $(7,6)$ MDS code to get coded symbols $\left(y_{1}, \ldots, y_{7}\right)$.
- Number of storage nodes $n=7$.
- Nodes correspond to lines in Fano plane.


## FR codes from combinatorial designs - Fano plane



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## FR codes from combinatorial designs - Fano plane



## FR code from Fano plane

 Analyzing file size- Nodes are 3-sized subsets. Using inclusion-exclusion principle

$$
\left|A_{1} \cup A_{2} \cup A_{3}\right|=\sum_{i}\left|A_{i}\right|-\sum_{i<j}\left|A_{i} \cap A_{j}\right|+\left|\cap_{i} A_{i}\right|
$$

- Depending on choice of
$A_{i}, i=1, \ldots, 3$, three-way
intersection can either be zero or 1 .
Minimum value is $3 \times 3-\binom{3}{2}=6$.
Hence, $k=3$.
- Failure recovery by contacting $d=3$ nodes.


## Key questions in FR code design

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- Can we construct FR codes that are flexible in the number of failures that they tolerate?
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- Can we construct FR codes that are flexible in the number of failures that they tolerate?
- Need flexible combinatorial designs: formalized in our work by resolvability.
- For a given FR code, can we determine the maximum file size that can be supported?
- Hard problem for a general combinatorial design. Need to find the minimum number of symbols covered over all $k$-sized subsets of the storage nodes; inclusion-exclusion analysis may not always be possible (though bounds can be obtained).
- FR codes with the same parameters ( $n, k, d, \theta, \alpha$ ) can have different file sizes.
- We determine file size for our constructions for certain parameter ranges.


## Key questions in FR code design

- How to calculate system metrics such as minimum distance?


## Definition

The minimum distance of a DSS denoted $d_{\text {min }}$ is defined to be the size of the smallest subset of storage nodes whose failure guarantees that the file is not recoverable from the surviving nodes under any possible recovery mechanism.

## Contributions of our work - I [Olmez \& R. 2012]

- Construct a large class of codes from resolvable designs where failure resilience of system can be varied in a simple manner (Prior constructions typically lack this flexibility).
- Simple implementation of repair table.
- Construct FR codes that cannot be constructed using Steiner systems
- Answers an open question raised in [El Rouayheb-Ramchandran '10].
- Determine the maximum supported file size for several parameter ranges.
- Prior work mostly provides lower bounds.


## Example of a resolvable FR with $\rho=2$ - Row-Column construction

$$
A=\begin{array}{lll}
1 & 2 & 3 \\
4 & 5 & 6 \\
7 & 8 & 9
\end{array}
$$

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 construction$$
\begin{aligned}
& A=\begin{array}{lll}
1 & 2 & 3 \\
4 & 5 & 6 \\
7 & 8 & 9
\end{array} \\
& 123 \quad 456 \\
& 147 \\
& 258 \\
& 369
\end{aligned}
$$

## Example of Parallel Classes

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## Resolvable fractional repetition code

## Definition

Let $\mathcal{C}=(\Omega, V)$ where $V=\left\{V_{1}, \ldots, V_{n}\right\}$ be a FR code. A subset $P \subset V$ is said to be a parallel class if

- $V_{i} \in P$ and $V_{j} \in P$ with $i \neq j$ we have $V_{i} \cap V_{j}=\emptyset$, and
- $\cup_{\left\{j: V_{j} \in P\right\}} V_{j}=\Omega$.
- A partition of $V$ into $r$ parallel classes is called a resolution.
- If there exists at least one resolution then the code is called a resolvable fractional repetition code.


## Example construction from 2-D subspaces of $\mathbb{F}_{3}^{3}$

There are thirteen two-dimensional subspaces of $\mathbb{F}_{3}^{3}$ which are the solutions to homogeneous linear equations over $\mathbb{F}_{3}$ in three variables.

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There are thirteen two-dimensional subspaces of $\mathbb{F}_{3}^{3}$ which are the solutions to homogeneous linear equations over $\mathbb{F}_{3}$ in three variables.

- Equation: $x_{1}=0$
- Subspace: $\{000,001,002,010,020,011,012,021,022\}$


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- Equation: $x_{1}=0$
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- Equation: $x_{1}+2 x_{2}+2 x_{3}=0$


## Example construction from 2-D subspaces of $\mathbb{F}_{3}^{3}$

There are thirteen two-dimensional subspaces of $\mathbb{F}_{3}^{3}$ which are the solutions to homogeneous linear equations over $\mathbb{F}_{3}$ in three variables.

- Equation: $x_{1}=0$
- Subspace: $\{000,001,002,010,020,011,012,021,022\}$
- Equation: $x_{1}+2 x_{2}+2 x_{3}=0$
- Subspace: $\{000,012,021,110,101,122,220,202,211\}$

The other blocks are additive cosets of these 13 representatives. For example,

$$
\begin{aligned}
& B_{1}=\{000,001,002,010,020,011,012,021,022\} \\
& B_{2}=\{100,101,102,110,120,111,112,121,122\} \\
& B_{3}=\{200,201,202,210,220,211,212,221,222\}
\end{aligned}
$$

## Observations



- $\left\{B_{1}, B_{2}, B_{3}\right\}$ covers 27 symbols - is a parallel class!


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- There are a total of 13 parallel classes.
- Two nodes from different parallel classes have exactly 3 symbols in common.
- Each symbol is repeated $\rho=13$ times.


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- Failure resilience can be varied from 1 to 12 failures! Significant flexibility as compared to Steiner systems considered in [El Rouayheb-Ramchandran '10].
- Simply choose an appropriate number of parallel classes.
- For failure recovery simply contact the intact parallel class.


## General Construction [OImez \& R. 2012]

## Construction

Given an affine resolvable design with parameters
$(n, \theta, \alpha, \rho)=\left(\frac{q^{m+1}-1}{q-1}, q^{m}, q^{m-1}, \frac{q^{m}-1}{q-1}\right)$ with blocks $B_{1}, B_{2}, \cdots, B_{n}$, an $F R$ code $\mathcal{C}$ can be obtained by taking $\mathcal{C}=\left\{B_{1}, B_{2}, \cdots, B_{n}\right\}$.

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The above construction yields an FR code with $\beta=\frac{\alpha^{2}}{\theta}$.

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$F R$ code $\mathcal{C}$ can be obtained by taking $\mathcal{C}=\left\{B_{1}, B_{2}, \cdots, B_{n}\right\}$.

Corollary
The above construction yields an FR code with $\beta=\frac{\alpha^{2}}{\theta}$.

- Ability to obtain codes with higher normalized repair bandwidth $\beta$. These parameters cannot be obtained by trivially treating each symbol in a smaller code as consisting of a larger number of symbols.


## Implications of result for $q=4, m=5, \delta=4$,

- Obtain a FR code with $\theta=1024$ symbols, storage capacity $\alpha=256$ symbols, normalized repair bandwidth $\beta=64$.
- Failure resilience can be varied from 1 to 340 !
- Prior constructions lack this flexibility.


## File size analysis [OImez \& R. 2012]

## Theorem

For $q>m$ and $m \geq k$, we can choose the parallel classes such that the file size $\mathcal{M}=q^{m}\left(1-\left(1-\frac{1}{q}\right)^{k}\right)$.

- File size analysis for FR codes is challenging as one needs to compute the minimum cardinality of the union of all $k$-sized storage nodes.
- However, careful analysis of the algebraic properties of the design can often help.


## Constructions from mutually orthogonal Latin squares

 (MOLS) [OImez \& R. 2012]$$
\begin{aligned}
& A=\begin{array}{cccc}
1 & 2 & 3 & 4 \\
5 & 6 & 7 & 8 \\
9 & 10 & 11 & 12 \\
13 & 14 & 15 & 16
\end{array} \\
& L_{1}=\begin{array}{llll}
1 & 2 & 3 & 4 \\
2 & 1 & 4 & 3 \\
3 & 4 & 1 & 2 \\
4 & 3 & 2 & 1
\end{array} \\
& L_{2}=\begin{array}{llll}
1 & 2 & 3 & 4 \\
3 & 4 & 1 & 2 \\
4 & 3 & 2 & 1 \\
2 & 1 & 4 & 3
\end{array} \\
& \text { - } L_{1} \text { and } L_{2} \text { are mutually } \\
& \text { orthogonal. } \\
& \text { - Choose blocks as elements of } A \\
& \text { corresponding to locations in } L_{i} \text {. } \\
& P^{L_{1}}=\{\{1,6,11,16\},\{2,5,12,15\}, \\
& \{3,8,9,14\},\{4,7,10,13\}\} \\
& \text { - Forms a parallel class. }
\end{aligned}
$$

$$
\begin{aligned}
P^{\text {rows }} & =\{\{1,2,3,4\},\{5,6,7,8\},\{9,10,11,12\},\{13,14,15,16\}\} \\
P^{\text {cols }} & =\{\{1,5,9,13\},\{2,6,10,14\},\{3,7,11,15\},\{4,8,12,16\}\} \\
P^{L_{1}} & =\{\{1,6,11,16\},\{2,5,12,15\},\{3,8,9,14\},\{4,7,10,13\}\} \\
P^{L_{2}} & =\{\{1,7,12,14\},\{2,8,11,13\},\{3,5,10,16\},\{4,6,9,15\}\}
\end{aligned}
$$

- For $N=p^{s}$, we can construct $N-1$ MOLS of size $N \times N$.
- For $N=p^{s}$, we can construct $N-1$ MOLS of size $N \times N$.
- If $N \neq 2,6$, constructions of two MOLS are known [Bose-Shrikhande-Parker '60].


## Implications of result

- We can construct a FR code starting with two MOLS of order 10 using [Bose-Shrikhande-Parker '60].
- However, Steiner system with storage capacity $\alpha=10$ and number of symbols $\theta=100$ does not exist.
- Equivalent to the existence of a projective plane of order 10 which is known not to exist [Lam et al. '89].
- Answers open question posed in [El Rouayheb-Ramchandran '10]


## Local Repair Example, $d<k$



- File $\left(x_{1}, \ldots, x_{5}\right) \in \mathbb{F}_{q}^{9}, \mathcal{M}=5$. Use $(9,5)$ MDS code to get coded symbols ( $y_{1}, \ldots, y_{9}$ ).
- Number of storage nodes $n=9$.
- Nodes store incident edge labels.


## Local Repair Example, $d<k$



- Failure recovery by contacting surviving nodes in the same column, $d=2$.
- Any four nodes cover $\mathcal{M}=5$ symbols, hence $k=4$.


## Local Repair Example, $d<k$



- Failure recovery by contacting surviving nodes in the same column, $d=2$.
- Any four nodes cover $\mathcal{M}=5$ symbols, hence $k=4$.
- Repair degree $d<k \ldots$
- Notion of local repair [Gopalan et al. '12, Papailopolous et al. '13, Oggier et al. '13]


## Contributions of our work - II [Olmez \& R. 2013]

- Constructions of locally recoverable FR codes.
- Local recovery from single failure - from high girth graphs.
- Local recovery from multiple failures - Collection of local FR codes. Global code inherits properties of the local one.
- Derive minimum distance bound for local, exact and uncoded repair. Our codes meet this bound for specific parameters.


## Locally Recoverable FR codes from high-girth graphs [OImez

 \& R. 2013]Local recovery from single failure.
An $(s, g)$-graph, denoted $\Gamma$ : vertex degree $s$, girth $g$.
(i) Index the edges from 1 to $\frac{n s}{2}$.
(ii) Each vertex $\equiv$ storage node; stores the symbols incident on it.

## Petersen Graph - degree 3, girth 5



- Parameters $n=10, k=5, \alpha=$ $3, \rho=2, d=3$ and $\mathcal{M}=10$.
- Can be shown that construction meets the minimum distance bound.

$$
d_{\min } \leq n-\left\lceil\frac{\mathcal{M}}{\alpha}\right\rceil-\left\lceil\frac{\mathcal{M}}{d \alpha}\right\rceil+2
$$

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$$

General result...
Theorem
Let $\Gamma=(V, E)$ be a $(s, g)$-graph with $|V|=n$ and $s>2$. If $g \geq k=a s+b$ such that $s>b \geq a+1$, then $\mathcal{C}$ obtained from $\Gamma$ is optimal with respect to the minimum distance bound when the file size $\mathcal{M}=k(s-1)$.

## Construction from collection of local FR codes

Pick FR code $(\Omega, V)$ with parameters $n$ - number of nodes, $\theta$ - number of symbols, $\alpha$ - storage capacity, $\rho$ - repetition degree, such that

- Any $\Delta+1$ nodes in $V$ cover $\theta$ symbols.
- Need to aim for a $\Delta$ that is somewhat low.
- Intersection size $\left|V_{i} \cap V_{j}\right|$ either equals $\beta$ or 0 .
- Allows for symmetric download.


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Construct $\overline{\mathcal{C}}$ by considering the disjoint union of $I(>1)$ copies of $\mathcal{C}$. Thus, $\overline{\mathcal{C}}$ has parameters $(\ln , I \theta, \alpha, \beta)$.

## Construction Example: Fano plane as a local FR code



- Parameters $(\theta, n, \alpha, \rho, \beta)=(7,7,3,3,1)$. Resilient up to two failures.
- Any $\Delta+1=5$ nodes cover all 7 symbols.
- Any 4 nodes covers at least 6 (Corradi's lemma).


## Construction Example

| $X_{1} X_{2} X_{4}$ | $X_{2} X_{3} X_{5}$ | $X_{3} X_{4} X_{6}$ | $X_{4} X_{5} X_{7}$ | $X_{5} X_{6} X_{1}$ | $X_{6} X_{7} X_{2}$ | $X_{7} X_{1} X_{3}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $Y_{1} Y_{2} Y_{4}$ | $Y_{2} Y_{3} Y_{5}$ | $Y_{3} Y_{4} Y_{6}$ | $Y_{4} Y_{5} Y_{7}$ | $Y_{5} Y_{6} Y_{1}$ | $Y_{6} Y_{7} Y_{2}$ | $Y_{7} Y_{1} Y_{3}$ |
| $Z_{1} Z_{2} Z_{4}$ | $Z_{2} Z_{3} Z_{5}$ | $Z_{3} Z_{4} Z_{6}$ | $Z_{4} Z_{5} Z_{7}$ | $Z_{5} Z_{6} Z_{1}$ | $Z_{6} Z_{7} Z_{2}$ | $Z_{7} Z_{1} Z_{3}$ |
| $T_{1} T_{2} T_{4}$ | $T_{2} T_{3} T_{5}$ | $T_{3} T_{4} T_{6}$ | $T_{4} T_{5} T_{7}$ | $T_{5} T_{6} T_{1}$ | $T_{6} T_{7} T_{2}$ | $T_{7} T_{1} T_{3}$ |

- 4 copies of Fano plane on: $X_{1}^{7}, Y_{1}^{7}, Z_{1}^{7}$ and $T_{1}^{7}$.
- $n=28, \theta=28$, repair degree $=3$.
- Any set of $k=15$ nodes cover at least 17 symbols, hence $\mathcal{M}=17$.
- Code resilient to 13 failures.
- Meets the minimum distance bound for locally recoverable FR codes that consist of local structures that are also FR codes.


## General result [OImez \& R. 2013]

## Theorem

Suppose that the parameters of the local $F R$ code satisfy
$(\rho-1) \alpha \theta-(\theta+\alpha)(\Delta-1) \beta \geq 0$. Let the file size be $\mathcal{M}=t \theta+\alpha$ for some $1 \leq t<I$. Then $\overline{\mathcal{C}}$ is minimum distance optimal.

- Condition allows us to estimate file size $\mathcal{M}$ using Corradi's lemma.
- Several local FR codes satisfy the condition.
- Affine resolvable FR codes.
- Projective plane based FR codes.
- Complete graphs, cycle graphs etc.


## Conclusions

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- Present a large class of resolvable FR codes. Allow the system designer to vary the repetition degree within a large range in a simple manner.


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- The systems under consideration require table-based repair. Resolvable nature of the code, makes the implementation of the table very simple.

Olmez \& R., "Fractional repetition codes with flexible repair from combinatorial designs", preprint 2014 (on arxiv).
Conference papers at Allerton 2012, NetCod 2013 and Asilomar 2013.

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- We also derive a minimum distance bound that is tighter in the case of codes with exact and uncoded repair.

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