Data Compression at High Sampling Rates

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Collaborators



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Field gathering:

Sampling, Encoding, Transporting, Reconstructing



Field-Gathering Wireless Sensor Network



- Sensors sample a field in two-dim'l region at discrete sequence of times.
- Each sensor source encodes its time-sequence of samples. This requires distributed lossy source coding.
- Communication network conveys bits to collector.
- Decoder at collector reconstructs snapshots of field (not just at sensor locations).
- We focus here on performance of source coding, not communication network.
- Competing Goals: minimize
 - rate = avg. number of bits per unit area per snapshot
 - MSE distortion, integrated over entire region

Centralized Coding



Distributed Coding



Principal Goals and Questions

Goal: design encoders and decoder to minimize coding rate subject to MSE distortion being at most target value *d*.

coding rate = bits/unit-area/time step

- sampling rate
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- For a given random field model X, class of coding schemes C, sampling rate S, and target distortion d, the coding rate per sample can be as small as the *operational rate-distortion function* $R_{X,C,S}(d)$.
- Hence, given X, C, S, d, coding rate can be as small as

$$S \times R_{X,C,S}(d)$$

- Goal: For different code classes C, find limit of $S \ge R_{X,C,S}(d)$ for large S.
- Question: Like which of the following does $S \ge R_{X,C,S}(d)$ behave?



Simplify to 1-dimensional, continuous-time signals

Not so much theory is known for source coding for continuous-time sources, even in 1-dimension

Four Classes of Lossy Source Codes to be Used with High-Rate Sampling

We'll analyze the following classes for stationary, Gaussian, continuous-time sources

- Transform + VQ
 - (centralized & optimal)

 Scalar quantization + entropy-rate coding: (centralized or distributed, no transform, suboptimal)

- Distributed VQ: (no transform, suboptimal)
- Transform + scalar quantization: (centralized, suboptimal)

Ideas Leading to a Conjecture

- For continuous-time source
 - Best performance of lossy source codes is given by Shannon rate-distortion function $R_{sh}(d)$.
 - For Gaussian source, a parametric expression for $R_{sh}(d)$ is known (Kolmogorov).
 - Performance as good as $R_{sh}(d)$ can be attained (to within ε) by sampling at very high rate, coding samples, and reconstructing cont.-time signal.
- For discrete-time (sampled) source
 - Best rate-distortion performance with distributed coding is not known, except for two Gaussian sources.
 - Uniform scalar quantization plus entropy-rate coding has performance close to $R_{sh}(d)$ for any discrete-time source.
 - Entropy-rate coding can be done in distributed fashion with as small rate as centralized coding. (Slepian-Wolf coding)
- Conjecture: uniform scalar quantization + distributed entropy-rate coding is distributed coding system that works well for cont-time source with high sampling rate (performance might be close to optimal).

(Idea: entropy-rate coding will exploit strong sample dependences to mitigate large sampling rate.)

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Four Strategies For Lossy Source Coding Based on High-Rate Sampling

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Review: Lossy Source Coding in Discrete-Time



Code: c = encoder & decoder (e.g. block code)

- Performance = rate & MSE distortion
 - R(c) = # bits/sample

$$- D(c) = \frac{1}{M} \sum_{i=1}^{M} E(X_i - Y_i)^2$$



- Operational rate-distortion function ORDF for class of codes C
 - $R_C(d) = \text{least rate of any } c \text{ in } C \text{ with } D(c) \leq d$
- Shannon rate-distortion theory: if C includes all block codes with all blocklengths $\mathcal{R}_{C}(d) = R_{sh}(d) \stackrel{\Delta}{=} \lim_{N \to \infty} \inf_{p(\underline{y}|\underline{x})} \frac{1}{N} I(\underline{X};\underline{Y}) \stackrel{\Delta}{=} \text{Shannon rate - dist'n func.}$ Example: IID Gaussian $R_{sh}(d) = \max\left\{\frac{1}{2}\log\frac{\sigma^2}{d}, 0\right\}$ High resolution theory: when d small $R_C(d) \approx \frac{1}{2}\log\frac{\sigma^2}{d} + \eta_{C,X}$
- where $\eta_{C,X}$ depends on class of codes and source statistics [Bennett, Zador].

ORDF: Block Codes & DT Gaussian Source

With orthogonal transform

$$R(c) = \frac{1}{M} \sum_{i=1}^{M} R(c_i), \quad D(c) = \frac{1}{M} \sum_{i=1}^{M} D(c_i)$$

Using optimal codes with distortions d_i

$$R(c) = \frac{1}{M} \sum_{i=1}^{M} \max\left\{\frac{1}{2}\log\frac{\lambda_i}{d_i}, 0\right\}$$

where $\lambda_i = e$. val. of cov. matrix K_M of \underline{X}
Minimize over $d_1, \dots, d_M \ge 0$ s.t. $\frac{1}{M} \sum_{i=1}^{M} d_i \le d$
to find there exists d' s.t.

$$d_i = \min \{d', \lambda_i\}, \text{ all } i,$$

$$R(d) = \frac{1}{M} \sum_{i=1}^{M} \max\left\{\frac{1}{2} \log \frac{\lambda_i}{d'}, 0\right\}$$



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Using optimal codes with distortions d_i $R(c) = \frac{1}{M} \sum_{i=1}^{M} \max\left\{\frac{1}{2} \log \frac{\lambda_i}{d_i}, 0\right\}$

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Minimize over $d_1, \dots, d_M \ge 0$ s.t. $\frac{1}{M} \sum_{i=1}^M d_i \le d$ to find there exists d' s.t.

$$d_i = \min \{d', \lambda_i\}, \text{ all } i,$$

$$R(d) = \frac{1}{M} \sum_{i=1}^{M} \max\left\{\frac{1}{2} \log \frac{\lambda_i}{d'}, 0\right\}$$

Convenient parametric form: $\theta \ge 0$

$$\widehat{d}_{M}(\theta) = \frac{1}{M} \sum_{i=1}^{M} \min \left\{ \lambda_{i}, \theta \right\}$$
$$\widehat{R}_{M}(\theta) = \frac{1}{M} \sum_{i=1}^{M} \max \left\{ \frac{1}{2} \log \frac{\lambda_{i}}{\theta}, 0 \right\}$$

Take M → ∞, using asympt. e. val. dist'n thm:

$$\widehat{d}(\theta) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \min\left\{\Phi(\Omega), \theta\right\} d\Omega$$
$$\widehat{r}(\theta) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \max\left\{\frac{1}{2}\log\frac{\Phi(\Omega)}{\theta}, 0\right\} d\Omega$$

where $\Phi(\Omega)$ is power spect. density of discrete-time process X.

[Kolmogorov `56]

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Operational rate-distortion function ORDF for class of codes C

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ORDF: CT Gaussian Source





[Kolmogorov `56, Berger `71]

Summary and Interpretaton



Examples



Heavier tailed spectrum \implies larger $\mathcal{R}(d)$ at small d.

Summary

For coding with transform and vector quantization.



Probably the middle one.

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Review: Centralized and Distributed Entropy-Rate Coding for Discrete-Time Source

- Entropy-Rate Coding (ERC)
 - The lowest rate with which a discrete-stationary source can be lossless encoded (for example with block-to-variable-length codes or conditional codes) its entropy-rate

$$H_{\infty} \stackrel{\Delta}{=} \lim_{L \to \infty} \frac{1}{L} H(X_1, ..., X_L) = \lim_{L \to \infty} H(X_L \mid X_1, ..., X_{L-1}) \text{ bits/sample}$$

Example: stationary Markov source $H_{\infty} = H(X_2 | X_1)$

ERC can be done in a distributed fashion at the same rate! [Slepian-Wolf `73]



Uniform Scalar Quantization (USQ) with ERC



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The Good News

Suppose we sample with rate N, quantize, entropy-rate code, and reconstruct cont-time signal.

- $-D \cong$ MSE of quantizer on samples; not affected by sampling rate
- $R = N \times R(c)$ bits/sec

 \cong *N* x $H_{\infty}(N)$ (entropy-rate is a function of sampling rate)

Theorem 1: [Marco-DN 2009]

For any stationary source and quantizer

$$H_{\infty}(N) \rightarrow 0$$
 as $N \rightarrow \infty$

Proof sketch: (recall *l_i* is index produced by quantizer in response to *X_i*) for any L,

$$\begin{aligned} H_{\infty}(N) &\leq LH(I_{1},...,I_{L}) &= \frac{1}{L}\sum_{n=1}^{L}H(I_{1} \mid I_{1},...,I_{n-1}) \\ &\leq \frac{1}{L}H(I_{1}) + \frac{L-1}{L}H(I_{2} \mid I_{1}) \quad \text{by stationarity} \\ &\rightarrow 0 \text{ as } N \rightarrow \infty \quad \text{because } \Pr(I_{2} = I_{1}) \rightarrow 1 \end{aligned}$$

The Bad News ... Conjecture is False

Theorem 2: [Marco-DN 2009]

For virtually any stationary source and quantizer

 $NH_{\infty}(N) \rightarrow \infty$ as $N \rightarrow \infty$



S = location of 1st threshold crossing in [0,1]; S = 2 if no crossing.

- $H(S) = \infty$, since S is rand. variable with a continuous component.
- From quantizer indices $I_1, ..., I_N$, can make estimate S_N of S s.t. $\left| S - S_N \right| \le \frac{1}{N}$ with high probability

This implies
$$H(S_N) \to \infty$$
.
Also $H(I_1,...,I_N) \ge H(S_N)$, since S_N is a function of $I_1,...,I_N$
Thus $\lim_{N \to \infty} N H_{\infty}(N) = \lim_{N \to \infty} N \frac{H(I_1,...,I_N)}{N} = \lim_{N \to \infty} H(I_1,...,I_N) = \infty$

¹Courtesy of Bruce Hajek

Another Explanation

 $\blacksquare R = N \times R(c)$

- \cong N x ($R_{sh,N}(d) + 0.255$)
- $= N \times R_{sh,N}(d) + N \times 0.255$

$$\rightarrow R_{sh}(d) + \infty$$

The weakness of this argument is that R(c) is small when N is large, whereas the high resolution approximation used is generally valid only when rate is large.

Summary

Bad news from Theorem 2: For scalar quantization and S-W distributed lossless coding,

et density N density N density N

- With identical scalar quantizers, when sensors are dense, entropy coding cannot sufficiently exploit increased correlation to mitigate increased number of sensors
- N.B.: It is not that field gathering with identical scalar quantizers is infeasible. But with such, there is a finite best sampling density.

 $N R_N(d) \rightarrow \infty$

At What Rate Does $NH_{\infty}(N) \rightarrow \infty$?

Theorem: [Marco-DN 2010] For unif. scalar quant. with step size Δ , infinitely many levels and stat'ry Gaussian $\mathcal{N}(0,\sigma^2)$ source with autocorr. func. $\rho(\tau)$,

$$NH_{\infty}(N) \leq H(I_1,...,I_N) \leq NH(I_2 \mid I_1) \approx -Nm\sqrt{1-\rho(1/N)} \log_2\sqrt{1-\rho(1/N)}$$

where

$$m = -\frac{2\sqrt{2}}{\pi} \sum_{k=0}^{\infty} e^{-\frac{(k+1/2)^2 \Delta^2}{2\sigma^2}}$$

Examples: When *N* is large,

$$\rho(\tau) = e^{-\tau/1} \implies NH(I_2 \mid I_1) \cong \frac{m}{2}\sqrt{N}\log_2 N$$

$$\rho(\tau) = e^{-\tau^2} \implies NH(I_2 \mid I_1) \cong \frac{m}{2}\log_2 N$$

Why Does Scalar Quantization Perform So Poorly With Dense Sensors?

- Is it a flaw of all distributed source coding schemes?
- Or just a flaw of scalar quantization based schemes?



- Consider Distributed Vector Quantization (VQ)
- Kashyap et al. [2005]
 - Showed that for a stationary, Gaussian source and ideal distributed lossy coding, $N R_N(d)$ remains finite as N increases.
- Pradhan & DN [2006,2013]
 - Made a similar analysis.
- Note: VQ dimension must increase with sampling rate N.

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Transform + scalar quantization:

(centralized, suboptimal)

Distributed Vector Quantization



- M sensors, 1/N apart in spatial interval [0, M/N]
- Spatial sampling rate = N
- For sampled source, R_{DVQ}(M,d) known only for M=2 Gaussian sources [Wagner, et al. 2007]
- Kashyap et al. [05] and Pradhan-DN [06,10] applied Berger-Tung bound [77] to obtain upper bounds to R_{DVQ}(M,d).

Berger-Tung Bound for Distributed VQ

Lower bound to least rate of distributed encoding of M sources with MSE d :

$$R_{DVQ}(M,d) \geq R_{BT}(M,d) = \inf_{p} \frac{1}{M} I_{p}(X_{1}...X_{M};Y_{1}...Y_{M})$$

where "inf" is over test channels with $MSE \leq D$.

Has same form as *M*-th-order Shannon rate-distortion function, except

Components of test channel are conditionally independent given source inputs

$$p(y_1,...,y_M \mid x_1,...x_M) = \prod_{i=1}^{M} p(y_i \mid x_i)$$

- In determining MSE, the test channel output $Y_1...Y_M$ is followed by an optimal estimator for inputs $X_1...X_M$ from source.

Applying Berger-Tung and Kuhn-Tucker

Choose test channel:

$$Y_i = \frac{1}{1+\Theta} (X_i + Z_i), \ i = 1,...,M$$

with Z_i 's IID, $\mathcal{N}(0,\theta)$

Use Kuhn-Tucker:

$$R_{BT,\theta} = \frac{1}{M} \sum_{I=1}^{M} \frac{1}{2} \log_2 \left(\frac{\lambda_i}{\theta} + 1 \right)$$
$$D_{BT,\theta} = \frac{1}{M} \sum_{I=1}^{M} \frac{\lambda_i \theta}{\lambda_i + \theta}$$

where $\lambda_1, \ldots, \lambda_M$ are the eigenvalues of covariance matrix of X_1, \ldots, X_M



Take limit as M →∞

Begin with

$$R_{BT,\theta} = \frac{1}{M} \sum_{I=1}^{M} \frac{1}{2} \log_2 \left(\frac{\lambda_i}{\theta} + 1 \right)$$
$$D_{BT,\theta} = \frac{1}{M} \sum_{I=1}^{M} \frac{\lambda_i \theta}{\lambda_i + \theta}$$

Let $M \to \infty$

$$R_{BT,\theta} \rightarrow \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{1}{2} \log_2 \left(\frac{\Phi(\Omega)}{\theta} + 1 \right) d\Omega$$
$$D_{BT,\theta} \rightarrow \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{\Phi(\Omega)\theta}{\Phi(\Omega) + \theta} d\Omega$$

for centralized VQ

$$\begin{split} R_{Sh,\theta} &= \frac{1}{M} \sum_{i=1}^{M} \max \left\{ \frac{1}{2} \log_2 \frac{\lambda_i}{\theta}, 0 \right\} \\ D_{Sh,\theta} &= \frac{1}{M} \sum_{i=1}^{M} \min \{\lambda_i, \theta\} \end{split}$$

$$R_{sh,\theta} \rightarrow \frac{1}{2\pi} \int_{-\pi}^{\pi} \max\left\{\frac{1}{2}\log_{2}\frac{\Phi(\Omega)}{\theta}, 0\right\} d\Omega$$
$$D_{sh,\theta} \rightarrow \frac{1}{2\pi} \int_{-\pi}^{\pi} \min\left\{\Phi(\Omega), \theta\right\} d\Omega$$

Let Sampling Rate $N \rightarrow \infty$

Change variables -- let $\omega = \Omega N$

$$R_{BT,\theta} \rightarrow \frac{1}{2\pi} \int_{-\pi N}^{\pi N} \frac{1}{2} \log_2 \left(\frac{\Phi(\omega/N)/N}{\theta/N} + 1 \right) \frac{1}{N} d\omega$$
$$D_{BT,\theta} \rightarrow \frac{1}{2\pi} \int_{-\pi N}^{\pi N} \frac{\Phi(\omega/N)}{\Phi(\omega/N) + \theta} \frac{1}{N} d\omega$$

Let sampling rate $N \to \infty$; let $\phi = \theta N$; then $\Phi(\omega/N)/N \to S(\omega)$ as $N \to \infty$

$$NR_{BT,\theta} \to \mathcal{R}_{BT,\theta} = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{1}{2} \log_2 \left(\frac{S(\omega)}{\theta} + 1 \right) d\omega$$
$$D_{BT,\theta} \to \mathcal{D}_{BT,\theta} = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{S(\omega)\theta}{S(\omega) + \theta} d\omega$$

This upper bound to optimal performance of distributed coding coding might be tight.

Comparison

Distributed Coding (attainable rate)

$$R_{BT,\theta} = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{1}{2} \log_2 \left(\frac{S(\omega)}{\theta} + 1 \right) d\omega$$
$$D_{BT,\theta} = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{S(\omega)\theta}{S(\omega) + \theta} d\omega$$

Centralized Coding (optimal rate)

$$R_{Sh,\theta} = \frac{1}{2\pi} \int_{-\infty}^{\infty} \max\left\{\frac{1}{2}\log_2\frac{S(\omega)}{\theta}, 0\right\} d\omega$$
$$D_{Sh,\theta} = \frac{1}{2\pi} \int_{-\infty}^{\infty} \min\{S(\omega), \phi\} d\omega$$

Distortion Profiles:



distributed coding cannot use transform, and so cannot have sharp cutoff bandlimiting.

Example

Source -- stationary, Gauss-Markov,

$$\rho(\tau) = e^{-|\tau|}, \quad S(\omega) = \frac{2}{1+\omega^2}$$



Distributed Coding (attainable rate)

Centralized Coding (optimal rate)

$$R_{BT}(d) = \frac{1}{2\ln 2} \left(\frac{1}{d} - 1\right)$$

$$R_{Sh}(d) \cong \frac{1}{2\ln 2} \left(\frac{0.81}{d} - 1 \right)$$
 for small d

= 6.5 bits/m

d = 0.1

= 5.1 bits/m

Example

d = 0.1

Source -- stationary, flat bandlimited

$$S(\omega) = \begin{cases} \pi/\omega_{o}, \ |\omega| \le \omega_{o} \\ 0, \ \text{else} \end{cases}$$



Centralized Coding (optimal rate)

$$R_{Sh}(d) = \frac{\omega_0}{2\pi} \log_2 \frac{1}{d}$$

= 1.7 bits/m

Distributed Coding (attainable rate)

$$R_{BT}(d) = \frac{\omega_0}{2\pi} \log_2 \frac{1}{d}$$

= 1.7 bits/m

Summary

For coding with distributed vector quantization.



Probably the middle one.

Are Scalar Quantizers Always Bad with Dense Samples?

Not always!

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 Transform + scalar quantization: (centralized, suboptimal)

- Proceed as before ...
- Sampling rate N rate over [0,∞)
- M-dimensional KLT produces Mindep. Gaussian coef's with variances equal to eigenval's of covar. matrix of $X_1, X_2, ..., X_M$: $\lambda_1^{(M)}, ..., \lambda_M^{(M)}$
- Independently scalar quantize and entropy code each type of transform coefficient, instead of optimally VQ encoding.
- Optimize the rate allocation for coefficients $r_1, r_2, ..., r_M$
- Take *M* to infinity.
- Take N to infinity.



Rate:
$$R = \frac{1}{M} \sum_{i=1}^{M} r_i$$

Distortion: $D = \frac{1}{M} \sum_{i=1}^{M} d_i$

- Let <u>R(d)</u> denote ORDF for scalar quantizing with entropy coding a unit variance Gaussian variable, Assume <u>R(d)</u> is convex.
- Then for i th coef. $r_i = \underline{R}\left(\frac{d_i}{\lambda_i^{(M)}}\right)$

Use Kuhn-Tucker theory to optimize d_i 's.



Given $\phi < 0$, Kuhn-Tucker gives

$$d_i = \lambda_i \underline{D'}(\phi \lambda_i)$$

where $\underline{D'}(\cdot)$ is the inverse of the derivative of $\underline{R}(\cdot)$

Substituting this gives optimal rate-distortion pairs, parameterized by ϕ

$$R_{Tr,\phi} = \frac{1}{M} \sum_{i=1}^{M} \underline{R}(\underline{D}'(\phi \lambda_i^{(M)}))$$
$$D_{Tr,\phi} = \frac{1}{M} \sum_{i=1}^{M} \lambda_i^{(M)} \min\{1, \underline{D}'(\phi \lambda_i^{(M)})\}$$

Dimension $M \rightarrow \infty$

$$R_{Tr,\phi} \to \frac{1}{2\pi} \int_{-\pi}^{\pi} \underline{R}(\underline{D}'(\phi \Phi(\Omega))) \, d\Omega$$

$$D_{Tr,\phi} \rightarrow \frac{1}{2\pi} \int_{-\pi}^{\pi} \min\{1, \underline{D}'(\phi \Phi(\Omega))\} d\Omega$$

• Change variables -- let $\omega = \Omega N$

$$R_{Tr,\phi} \rightarrow \frac{1}{2\pi} \int_{-\pi N}^{\pi N} \frac{R(\underline{D}'(\phi \Phi(\omega/N)))}{N} \frac{1}{N} d\omega$$
$$D_{Tr,\phi} \rightarrow \frac{1}{2\pi} \int_{-\pi N}^{\pi N} \min\{1,\underline{D}'(\phi \Phi(\omega/N))\} \frac{1}{N} d\omega$$

Sampling rate $N \to \infty$, let $\phi = \theta N$, $\Phi(\omega / N) / N \to S(\omega)$ as $N \to \infty$

$$NR \rightarrow R_{Tr,\theta} = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{R}{2\pi} \left(\frac{D'}{\theta} \right) d\omega$$
$$D \rightarrow D_{Tr,\theta} = \frac{1}{2\pi} \int_{-\infty}^{\infty} S(\omega) \min\left\{ 1, \frac{D'}{\theta} \right\} d\omega$$

To repeat

$$R_{\mathrm{Tr},\theta} = \frac{1}{2\pi} \int_{-\infty}^{\infty} \underline{R} \left(\underline{D}' \left(\frac{S(\omega)}{\theta} \right) d\omega \right)$$
$$D_{\mathrm{Tr},\theta} = \frac{1}{2\pi} \int_{-\infty}^{\infty} S(\omega) \min \left\{ 1, \underline{D}' \left(\frac{S(\omega)}{\theta} \right) \right\} d\omega$$

- Since these are finite, scalar quantization does not lead to catastrophic performance, provided it is preceded by a transform.
- Note: If <u>R(.)</u> is replaced by Shannon rate-distortion function for Gaussian samples, the above reduces to Shannon rate-distortion function for continuous-time Gaussian source.
- [Pradhan-DN, 2007,13]

Why Does Transform Coding With Scalar Quantization Not Suffer Catastrophically Bad Performance?

Without transform, scalar quant. + ent. coding has rate

 $R_N(d) \approx R_{sh,N}(d) + O(1)$

$$R \approx N R_N(d) + NO(1) \rightarrow R_{Sh,N}(d) + \infty$$

- However: O(1) "loss" goes to zero as d approaches variance.
- With KLT, variances are eigenvalues.
- **Lemma:** For any $\delta > 0$, fraction of eigenvalues $> \delta$ goes to zero.
- With transform coding

$$R \approx N \frac{1}{M} \sum_{i=1}^{M} r_i = N \frac{1}{M} \sum_{i=1}^{M} \frac{d_i}{\lambda_i^{(M)}}$$

For most *i*, $d_i \approx \lambda_i$, so there is virtually no loss \Rightarrow overall loss is small.

<u>\</u>



Summary

For coding with transform and quantization.



Probably the middle one.

Overall Summary

- Can attain optimal rate-distortion performance with high-rate sampling and transform coding
- Can attain good rate-distortion performance with high-rate sampling and
 - Transform coding with scalar quantization
 - Distributed coding
- Cannot attain good rate-distortion performance with high-rate sampling and direct scalar quantization, even with entropy-rate coding.
- To attain good performance, the dimension of the quantizer (in time) must grow as sampling rate grows.
- If one wishes to use scalar quantization plus ERC, one should not use too large a sampling rate, because entropy-rate does not decrease fast enough to mitigate the effect of high sampling rate.
- In centralized transform coding, scalar quantization does not cause a problem because most coefficients are scalar quantized at very low rates at which there is very little loss relative to high-dimensional VQ.

Ongoing Work

- High-resolution, high-sampling-rate analysis:
 - We are finding closed form expressions for ORDF $R_C(d)$ for distributed and transform coding when sampling rate is large and distortion d is constrained to be small.
- Convergence of discrete-time power spectral density to continuous-time power spectral density:
 - We are identifying conditions under which one can rigorously prove

 $N\Phi_N(N\omega) \rightarrow S(\omega)$ as $N \rightarrow \infty$

and finding counterexamples, where conditions do not hold.